

Dealing with error in applications

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Why we do this

- **Application should adhere to one principle of dealing with errors. This makes understanding of the software easier.**
- **We want to be able to collect errors in an integral way:**
 - Dealing with error text
 - Dealing with error description
 - Logging of errors
 - Documentation of errors

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Representing errors

Error is 32 bit integer containing:

- **Severity**
 - Oke: Success, Informational
 - Not Oke: Warning, Error, Severe
- **Facility**
 - Unique number of this error range
- **Error number**
 - Unique number of the error with the facility

Representation copied from VMS

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How to use inside code (1)

Routine return error code

```
procedure dosomething (..... Error : out Integer);  
begin  
    ...  
    Error := Mot_Useerror;  
    ...  
end
```

After calling always check the error

```
dosomething (Error);  
if Status_Oke (Error) then  
    ...
```

How to use inside code (2)

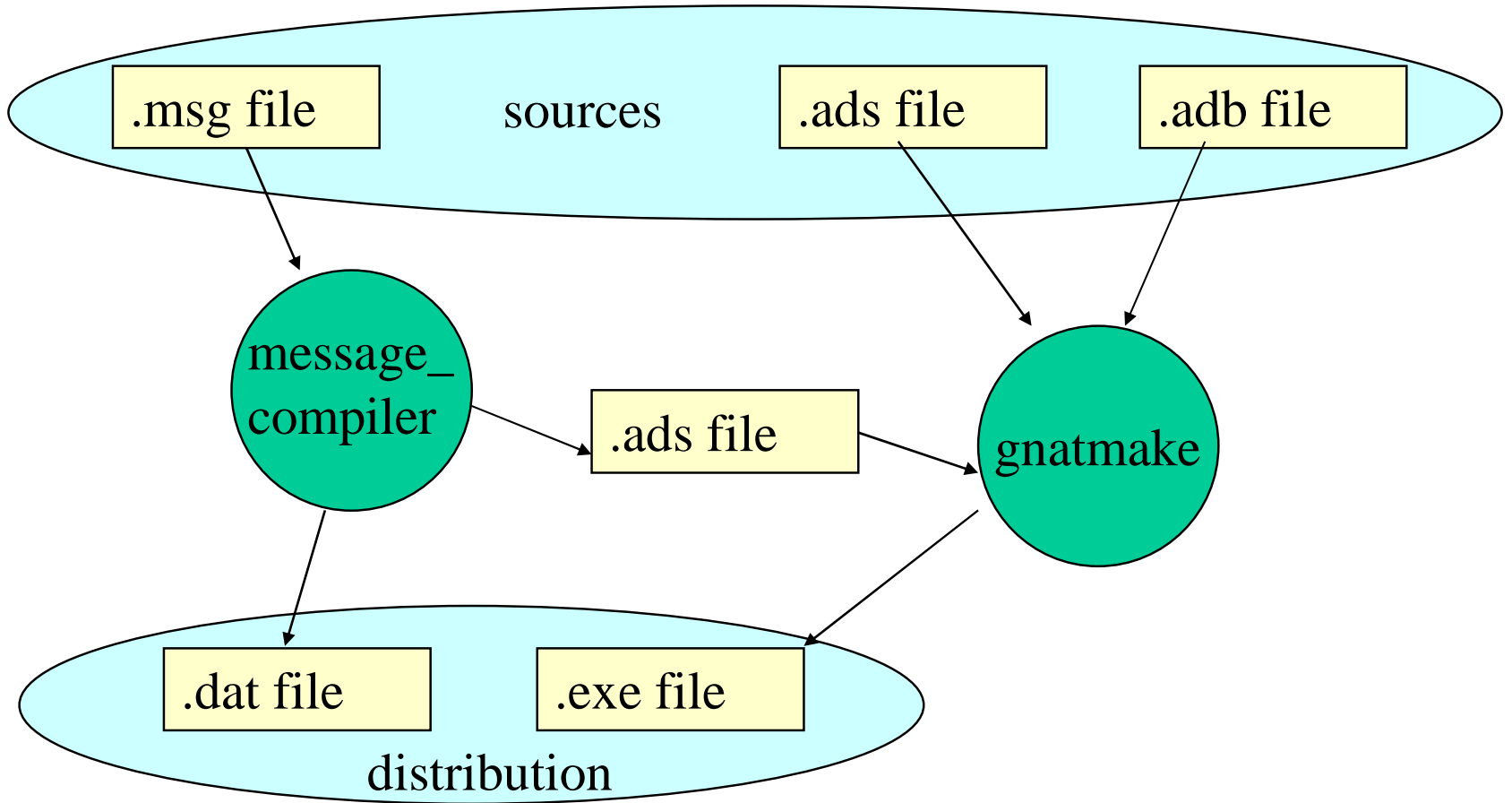
Routine raises exception with that error code

```
procedure dosomething (..... );  
begin  
  ...  
  Raise_Exception (Mot_Useerror);  
  ...  
end
```

To catch error use exception handler:

```
begin  
  dosomething (...);  
exception when E : others =>  
  -- exception handling code  
end;
```

Building cycle



PS - XXX.XX.XX-6

Contents of .msg file

```
.facility Mot,3
```

Facility name

```
.severity error
```

```
!-----  
! The following errors are software errors
```

Brief error description

```
!-----  
! UseError
```

Error name

```
UseError <Wrong use, calling routine when not allowed>
```

```
! Some internal error detected. Report to ITEC.
```

```
MotorNotReady <Motor not ready>
```

```
CommunicationError <Communication error>
```

```
EncoderDisconnect <Encoder disconnect>
```

```
! The encoder seems no longer to be connected to the motion
```

```
! Controller. Please check the cabling of it.
```

```
.end
```

Full error description

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Support packages

Package Eln

```
Success : constant Integer := 1; -- Success status  
function Status_Oke (Status : Integer) return Boolean;
```

Package Eln.Exceptions

```
function Exception_To_Status (X : Exception_Occurrence) return Integer;  
procedure Raise_Exception (Status : Integer);  
function Status_To_Text (Status : Integer) return String;  
function Status_To_Description (Status : Integer) return String;
```


Integration into Visual ITEC

Dealing of status codes within Visual ITEC

- When `visual_itec` knows something is a status, it will display the proper text (`Status_To_Text` result) and have a proper tooltip (`Status_To_Description`).

How to let Visual ITEC know:

- Returning a status as item text: use `make_status`
- When `exec_command` or `modify_item` calls fail: return proper status

Error logging

We call it ESM: Equipment status monitoring.

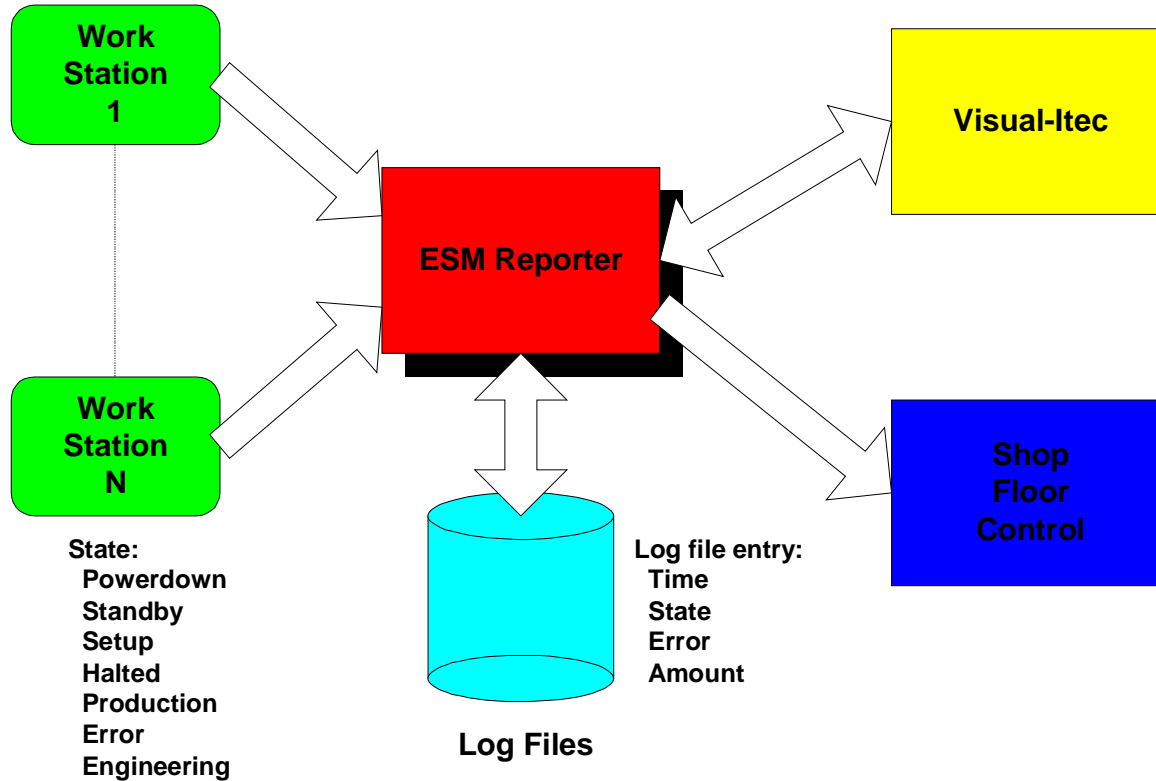
We log:

- **Time**
- **Errors**
- **State changes**

When error log component build in the application it adds the following functionality:

- **Life pareto of errors that have occurred**
- **Percentage of time spend in states**
- **Command to reset the .esm file (clears the history)**

ESM software component



PS - XXX.XX.XX-11

Conclusions

Error mechanism used in all our applications

Results:

- **Easy and simple way to deal with errors**
- **Error unique over all applications**
- **Also solves documentation of errors:**
 - **Tooltips show descriptions**
 - **Possible to build list of errors + descriptions automatic**
- **Allows logging of errors in a integral and compact way**

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