



ASML

**Connectivity in the large –
*a new challenge for us system engineers***

SASG meeting 4-feb-2013
Tom Hoogenboom, ASML

Summary

- Auto Motive – from connectivity in the small
– to connectivity in the **large**
- System of Systems Engineering
- A new opportunity for age-old annoyances
- A new responsibility for system engineers



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Auto Motive

AUTO = self

MOTIVE = moving



Automotive is not Auto Motive

- Cars do not drive themselves

Automotive can be automotive

Cars do not
drive themselves?

The New York Times

October 10, 2010

Autonomous Driving

Google's modified Toyota Prius uses an array of sensors to navigate public roads without a human driver. Other components, not shown, include a GPS receiver and an inertial motion sensor.

LIDAR

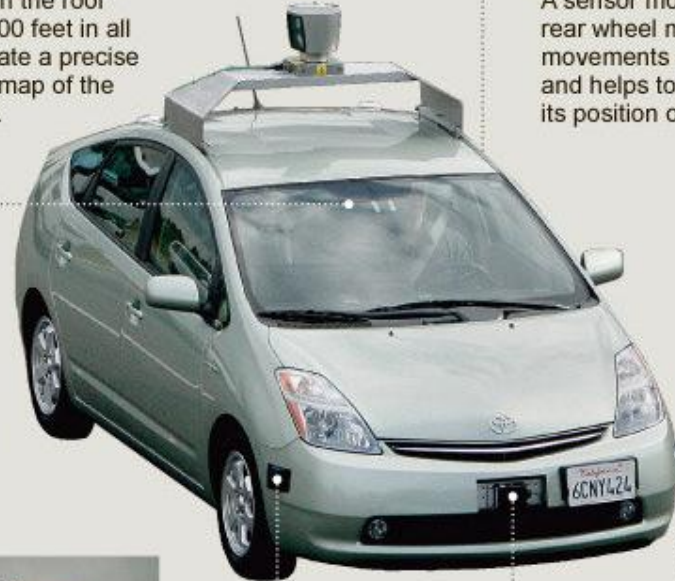
A rotating sensor on the roof scans more than 200 feet in all directions to generate a precise three-dimensional map of the car's surroundings.

POSITION ESTIMATOR

A sensor mounted on the left rear wheel measures small movements made by the car and helps to accurately locate its position on the map.

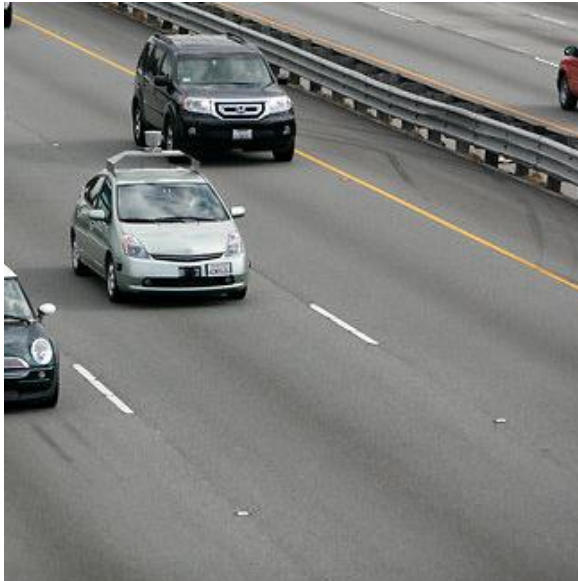
VIDEO CAMERA

A camera mounted near the rear-view mirror detects traffic lights and helps the car's onboard computers recognize moving obstacles like pedestrians and bicyclists.



RADAR

Four standard automotive radar sensors, three in front and one in the rear, help determine the positions of distant objects.



Source: Google

THE NEW YORK TIMES, PHOTOGRAPHS BY RAMIN RAHIMIAN FOR THE NEW YORK TIMES



Connectivity in the small

- Inside
 - LIDAR
 - Front and rear cameras
 - Position sensors
 - GPS
 - RADAR
 - Etc. etc.
 - Plus engine control computer, fuel sensors
 - Plus sensor signal processing IC
 - Plus....



Connectivity in the large

- Outside
 - Pedestrians
 - Road marking
 - Traffic lights
 - Traffic control systems
 - **GPS satellites**
 - **plus...**



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Systems engineering

- Optimize 1 system
 - For 1..n environments
 - To sell 1..n copies

System of Systems Engineering (SoSE)

- SoSE goal:
 - optimize network of various interacting systems
 - Both legacy and new
 - brought together to satisfy multiple objectives
 - Including evolution of the SoS over time

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Consider multiple 'automotive' cars



Model, say, The Netherlands as one big network

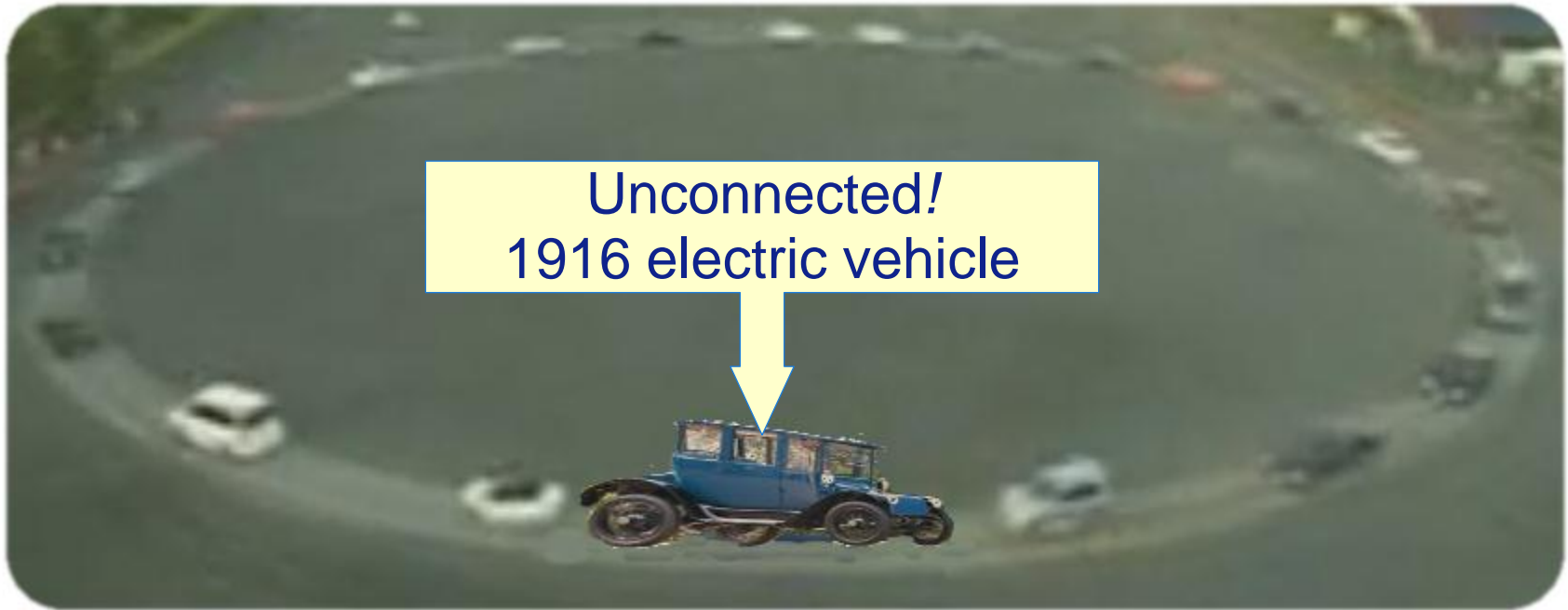


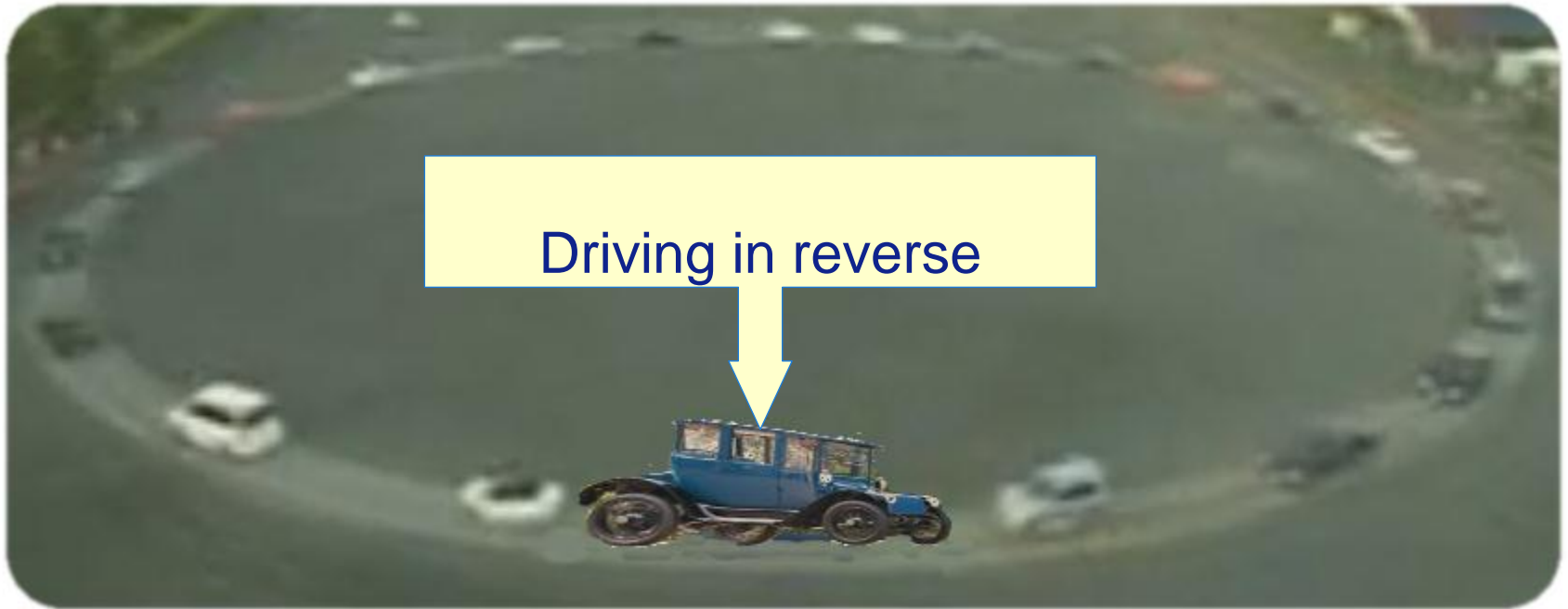


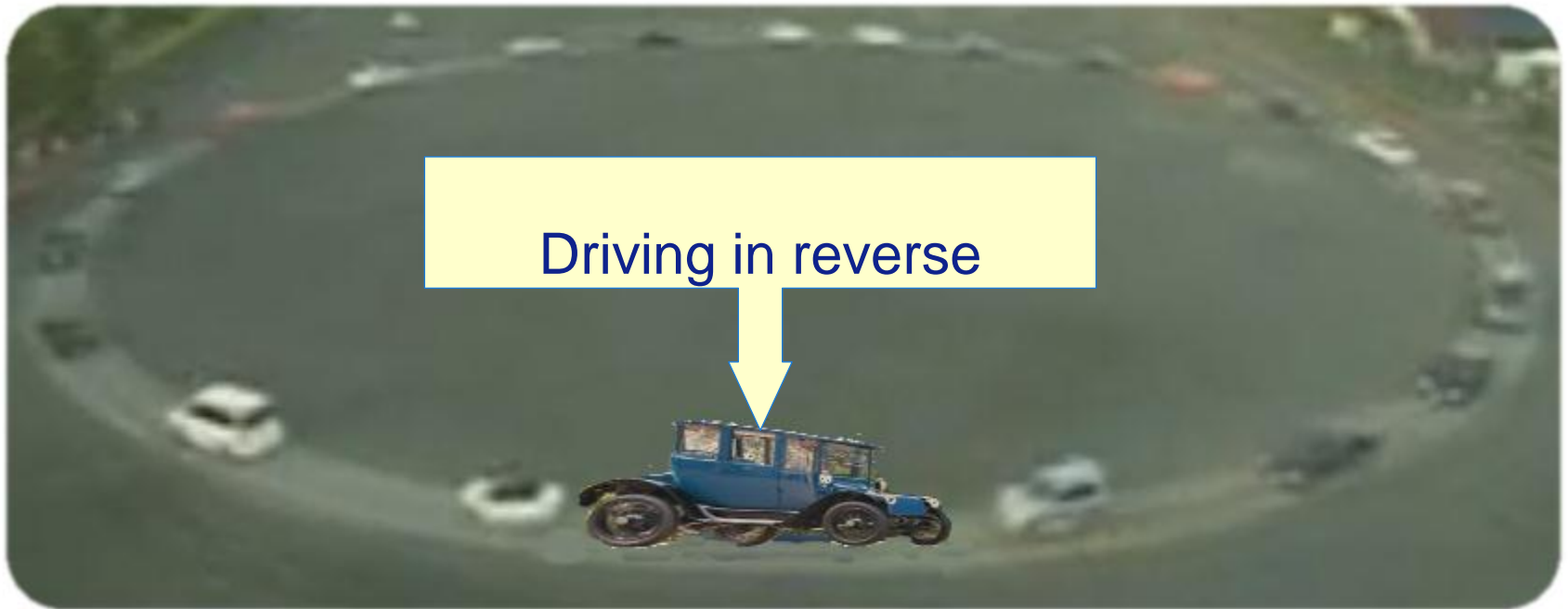


This one just broke
down – 70 km traffic jam

→ new reliability issues emerge







→ System-of-systems must cope with legacy components






This one cheated....

It hacked the emergency services system.
Cars nearby were diverted to create a free road



An aerial photograph of a roundabout with several cars. A yellow text box with a red border is overlaid on the image, containing text. A large yellow arrow points downwards from the text box towards a white car in the center of the roundabout.

It hacked the emergency services system.
Cars nearby were diverted to create a free road

→ System-of-systems must cope with security issues

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So we must consider a complex environment which evolves over time

- Reliability for an ensemble of N systems with $N > 1000000$.
- Protect privacy and prevent hacking
- Address security issues that could affect a whole country

Final Summary

- Auto Motive – from connectivity in the small
– to connectivity in the **large**
- System of Systems Engineering is a new discipline
- A new opportunity for age-old annoyances like reliability
- A new responsibility for system engineers:
integration of systems evolving over time

To trigger discussions – 4 statements

- 1- small scale connectivity,
e.g. canBus,
reliability spec must have N cars in mind, not 1
→ reduced risk of traffic jams in The Netherlands

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must be such that hacking is prevented
→ users must accept loss of privacy
- 3- large scale connectivity
e.g. Tom Tom networks
must prevent hijacking of system functionality
→ engineers must consider new failure modes

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4- System-of-system integration must be coordinated

across all levels of connectivity

by a body with sufficient authority to enforce security, privacy and reliability.

